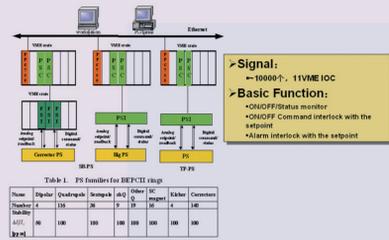
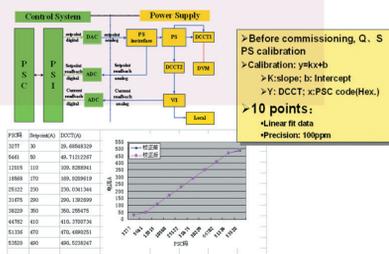


The Upgrade Project of Beijing Electron Positron Collider (BEPCII)

PS Control System



PS Control Calibration



PS OPI

- There are 3 logical rings called BSR, BER, BPR.
- 4 panels per ring (BSR/BER/BPR):
 - B, Q, S Monitor
 - B, Q, S ON/OFF
 - Corrector Monitor
 - Corrector ON/OFF

BPR PS Monitor

- Left: region 2, 3, Right: region 1, 4
- 8 row info, Magnet/Status/Arms/DESIMON/Setpoint/Current
- Ramping/STDZ/Execution Status Monitor



PS Control Commissioning

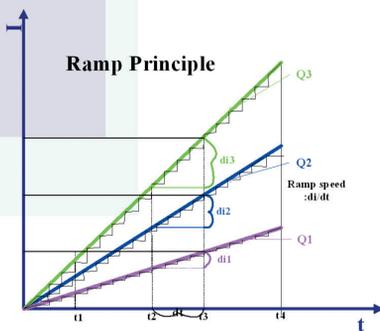
- Device commissioning started region by region
- On one hand magnets were installed, on the other hand magnet PS remote controls were tested
- Short time for All PS control testing with the magnets
- PS ramping region by region put into operation at the beginning of the beam commissioning
- After the commissioning, start to develop the ramping program of the entire ring BSR
- Short testing time for ramping program

PS Ramping

- SR First Running: 2006.12.25 - 2007.2.2
- Important Issue: Energy Ramping in BSR
- Requirements:
 - All PS in BSR are ramped to the desired value synchronously (from 1.89GeV to 2.5GeV)
- Implementation:
 - PS Control distributed (11 VME IOC)
 - Ramping program in every IOC
 - EPICS event to trigger every ramping program
 - Real-time DB processing slow (60Hz clock), different CPU load, synchronization problem
 - Ramping program in an independent VME IOC
 - Change EPICS clock from 60Hz to 600Hz
 - Real-time database processing fast
 - write setpoint to setpoint DB of the all IOCs step by step
 - Ramping procedure is getting fast

Linear Ramping Principle

- The maximum steps of the power supplies can be calculated according to the given maximum delta per step and given initial and final current.
- The number of steps is determined by the formula: (desimon-setpoint)/delta.
- The program sends out different setpoints step by step so that the power supplies can be set to their own desired value.



B, Q, S PS Control Distribution

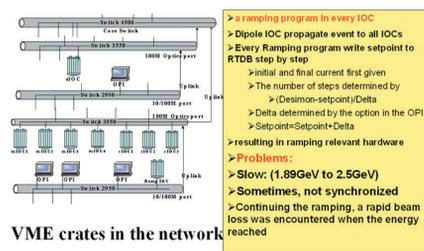


- PS distribution is different, B PS independent, Q/S PS+ DC PS
- 1 DC power to 10 choppers, for example: 5 OQ and 5 IQ
- Different PSC number in each VME crate:
 - PVs Num. Different, Different CPU load
 - EPICS default clock: 60Hz PVs processing slow
 - Ramping Program in each IOC: not synchronously

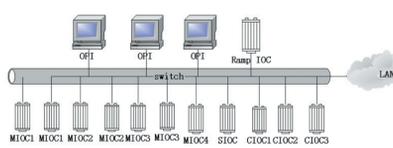
Three Stage Testing

- Stage 1 (first half of Dec. 2006)
 - A ramping program in every IOC
 - EPICS IOC clock 60Hz
- Stage 2 (second half of Dec. 2006)
 - A ramping program in an independent IOC
 - EPICS IOC clock 60Hz
- Stage 3 (Jan. 2007)
 - A ramping program in an independent IOC
 - Change EPICS IOC clock from 60Hz to 600Hz

Stage 1 (2006.11-2006.12)

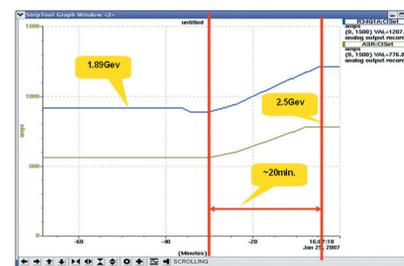


Stage 2 (06.12)



- Re-arrange VME IOC distribution in the network
- All IOCs are connected to a way to minimize the unrelated network traffic.
- EPICS clock 60Hz
- A ramping program in an independent IOC, no synchronization problem
- Ramping Slow: 20 min. (1.89GeV to 2.5GeV)
- Reason:
 - EPICS clock 60Hz resulting PVs processing slow
 - Time interval between two steps must be long enough

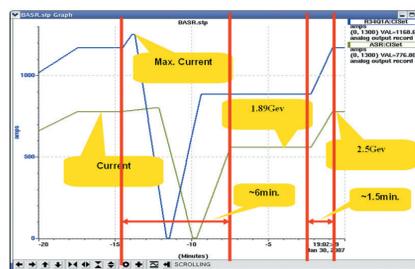
Testing Results



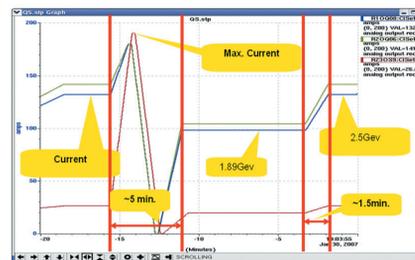
Stage 3 (Jan. 07)

- Change EPICS clock from 60Hz to 600Hz
- Testing with beam (2 times) (On Jan. 30)
 - Current=46mA, slow speed, delta=0.5A, Ramping from 1.89GeV to 2.5GeV: 5 min. no beam loss
 - Current=47.89GeV, fast speed, delta=1.0A Ramping from 1.89GeV to 2.5GeV: 1.5 min. a little bit beam loss
- Testing with beam (on Feb. 4)
 - Current=250mA, fast speed, delta=1.0A Ramping from 1.89GeV to 2.5GeV (with 3 stops): ~1.5min. No beam loss
 - Continuing the ramping, a beam loss was encountered when the energy reached

Testing results



Testing results



BSR Monitor and Ramping OPI

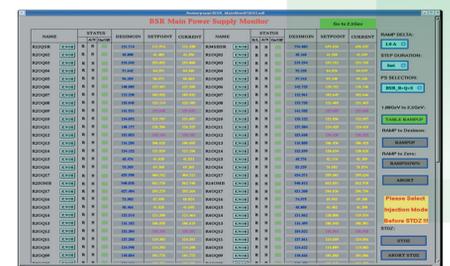
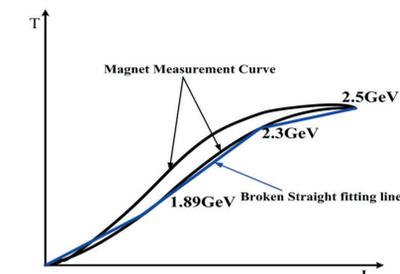


Table Ramping

- In order to ensure continuous ramping without the beam loss, we used two broken straight line instead of one straight line to fit the magnet measurement curve.
- The advantage of this way is that the current setpoints are closer to the magnet measurement data.
- One broken straight line is for 1.89GeV to 2.3GeV, another is for 2.3GeV to 2.5GeV.
- The energy and designed current values are saved into the database running on a soft IOC.
- The ramping program can get the designed current value by setting the energy.

Table Ramping

- For eg. The ramping program set 2.3GeV energy to the energy PV, then get the designed current values at 2.3GeV, calculate delta from the current setpoint values to the designed current values, linear ramping to 2.3GeV, then get the designed current values at 2.5GeV, go same way, up to 2.5GeV.
- The whole procedure is done by one button "Table Ramp". By testing with the beam, there was no beam loss happened. It took about 2 min.
- The ramping program was put into the second synchrotron running (May-July, 2007)
- It was going very well.



Summary

- Ramping program has a enough fast speed now
- Improvement on Ramping Quality with beam
- Different magnets, different PS, different magnetic field response
- Energy ramping in BSR has been running very well.
- It play an important role in BEPCII synchrotron radiation running.

Energy(B current)/Lifetime/ Current Ramping no beam loss

